Improved Magnetic Sensor for Oil and Natural Gas Well Logging

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Motivation and Objectives

Motivation: Reduction of high ringing in magnetic sensor

Project Objectives:

- Produce a low magnetic field sensor with high signal to noise ratio
- Reduce or eliminate unwanted resonances
- Redesign measurement setup to include uniform external magnetic field
- > Automation of signal processing

Requirements

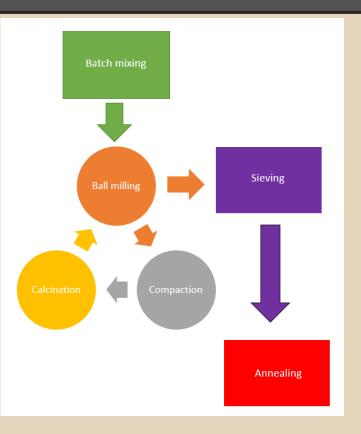
Functional

- Soft magnetic core
- Rod-like geometry
- Reduce unwanted resonances
- Low hysteresis losses
- Uniform magnetic field of 400 G encompassing length of ferrite core

Non-Functional

- Must be one of the materials currently being explored by the client
- Preparation at Ames Lab or the Microelectronic Research Center (MRC)

Sample preparation

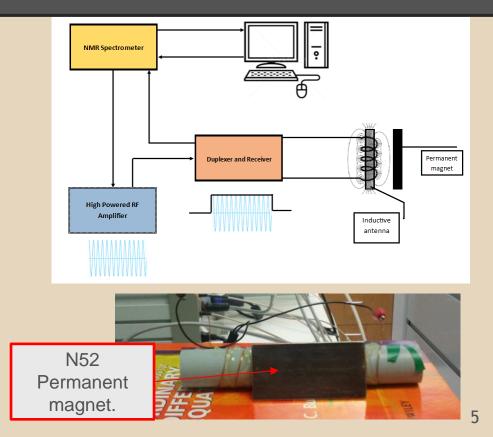


- First sample is NiZnFerrite+epoxy
- Sample to epoxy ratio 25:75
- Calcination at 1050 1100 °C.
- Two phase microstructure with annealing

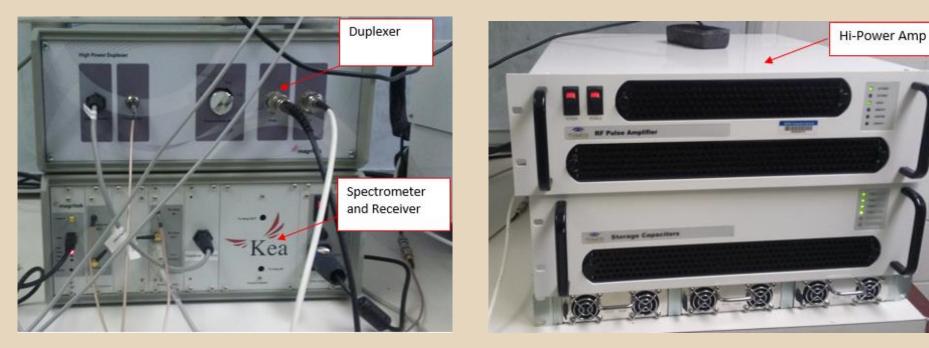


Measurement setup

- User defines pulse frequency
- Sent to NMR spectrometer
- Routed to the high power RF amplifier
- Sent to duplexer which filter's out unwanted signals
- Sent to inductive antenna
- Response sent to receiver
- Routed to the NMR spectrometer

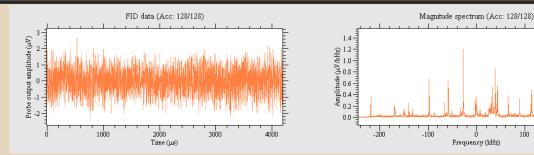


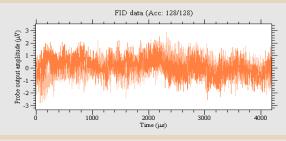
Actual measurement setup

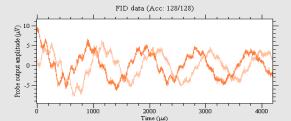


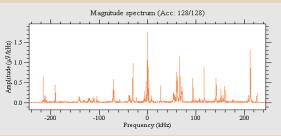
Resonant peaks identification

- Identify all possible peaks from 0.1 MHz to 1.2 MHz
- Find the spectral bandwidth
- Reciprocity between spectral bandwidth and the damping of oscillations
- Time domain signals which die out quickly most likely to be noise
- Develop software that can find spectral bandwidth of multiple data files

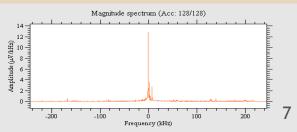






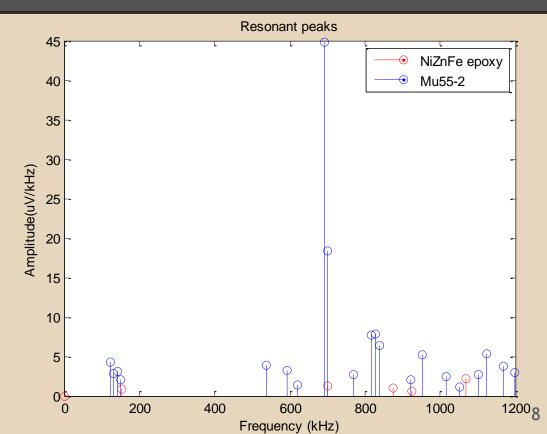


200

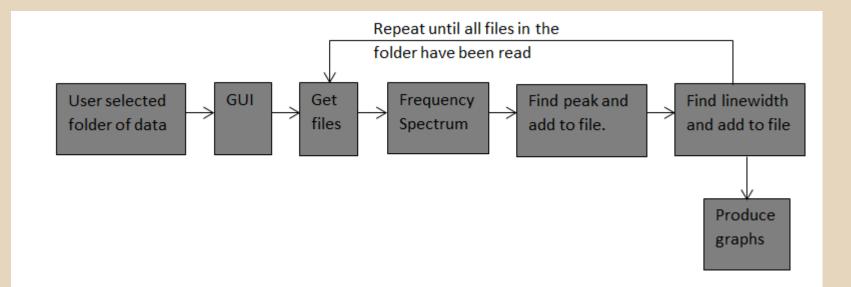


Sample comparison.

- NiZnFerrite+epoxy has fewer peaks
- The Mu55-2 has more peaks and higher amplitude peaks
- Need to test all the other samples and see how they compare



GUI system



The approach

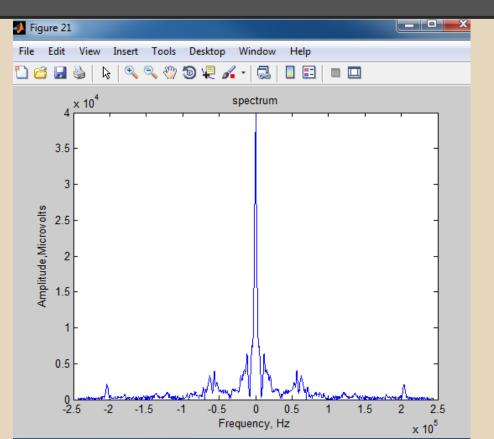
The signal processing relies on three functions

Function Name	Function Purpose
fouriertransform	Transforms the data to the frequency spectrum.
peakdetect	Creates and array of all the peaks present in the
	data and finds the one closest to the pulse
	frequency
linewidth	For each file it takes the peak returned by peak
	detect and finds the point at which that peak is at
	half its maximum. It then determines the width of
	the peak at that point.

How the processing works

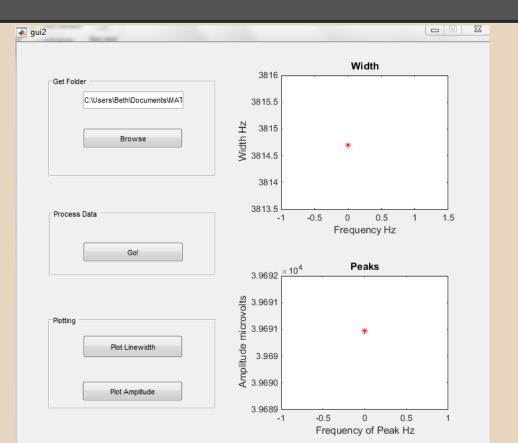
- Frequency spectrum->FFT function
- Peak Detection looks for point greater than both its neighbors
- Half-Width maximum->go to peak and move left until half the peak value is achieved. Multiply by 2

Find signal spectrum

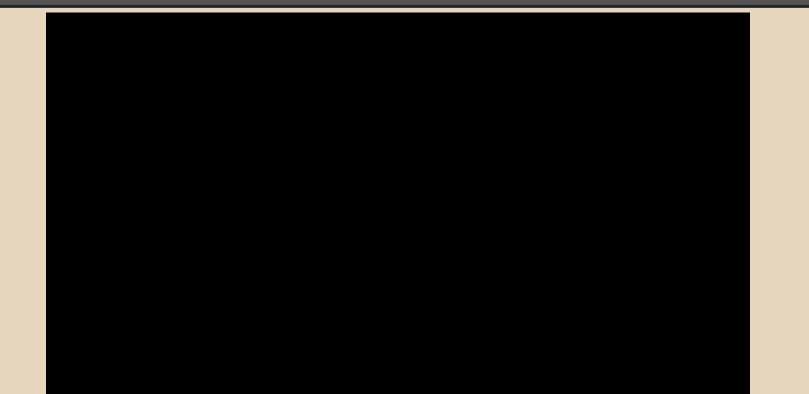


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The GUI

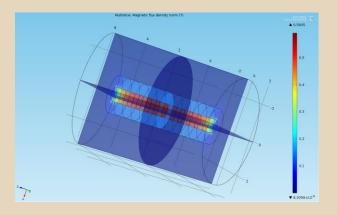


Code demo



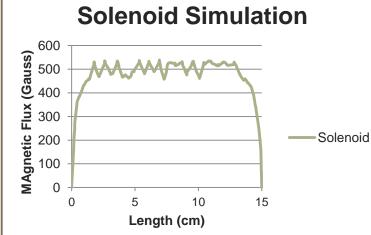
Uniform permanent magnetic field

- Induces external static magnetic field
- Magnetizes material in the core
- Low field (400 Gauss) allows the probe to have wide detection range including both oil and water resources
- External field geometries were simulated using COMSOL



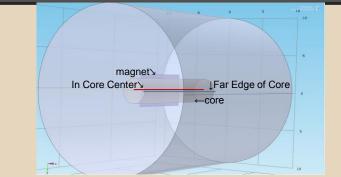
Solenoid solution

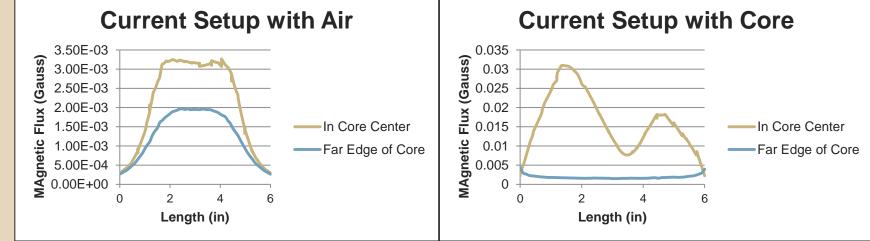
- \blacktriangleright Used solenoid equation: B = $\frac{\mu IN}{T}$
- > B = Magnetic flux density, μ = Permeability I = Current, N = Number of turns, L = Length of coil
- Solenoid Specifications:
- ➤ I = 3.1A, N = 1550, L = 15, B = 402.543G
- Trial with 19 gauge wire, N =109, I = 0.5 A, B = 8 G
- 40 gauge laminated copper wire will be used for final build
- > Simulations run with UNS C10100 Copper, $\mu_r = 6.8$



Current setup

- Permanent magnet block: 1/8 in. by 3/4 in. by 3/2 in.
- Magnet 1/4 in. away form core material
- Magnetic field defined radially

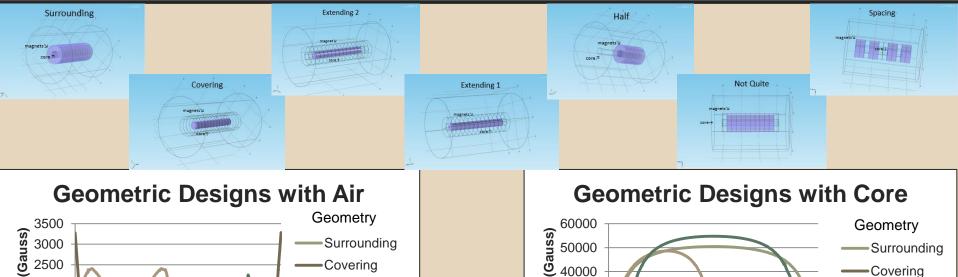




Basics Of Permanent Magnet Simulation

- > Permanent Magnet: NdFeB, $\mu_r = 1.5$
- \succ B = $\mu_r \mu_0 * B_{rmax}$
- \succ Residual induction B_{rmax} = 13,200 Gauss
- > Soft core: Mg₉₇ZnGd₂[solid, treated at 793K], $\mu_r = 1500$
- Magnetic flux measured axially
- Magnetic flux density plotted in Gauss
- Simulation defined in inches to reflect actual geometry of permanent magnets
- Magnets chosen to keep costs reasonable

Geometry



40000

30000

20000

10000

0

0

2

Length (in)

Flux

MAgnetic

-Covering

Extending 2

Extending 1

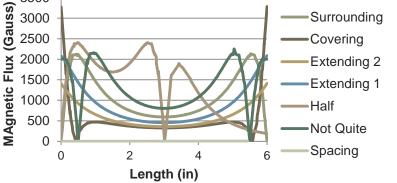
-----Half

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—Not Quite

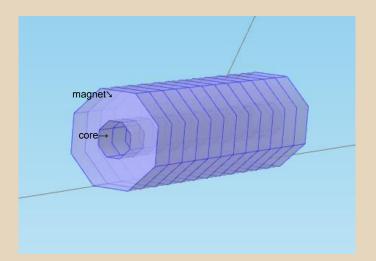
Spacing

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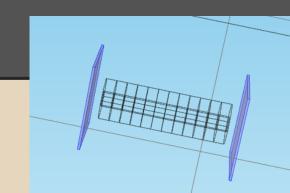


Shielding

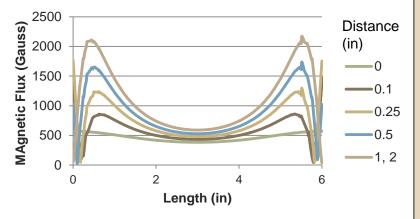
- Shielding idea from errors in surrounding geometry interacting with magnetic flux
- Material: Udimet400
- \succ $\mu_{\rm r} = 80,000$
- > 60 % nickel
- > 1/10 in. thick
- All use the Surrounding geometry



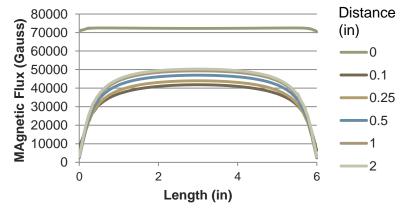
Blocks



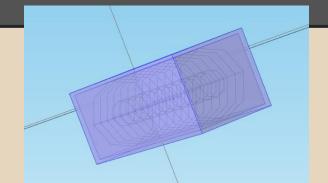
Shielding Blocks at Ends with Air



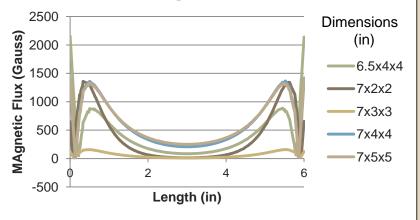




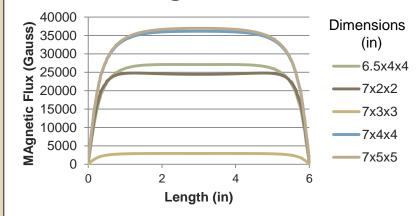




Shielding Box with Air

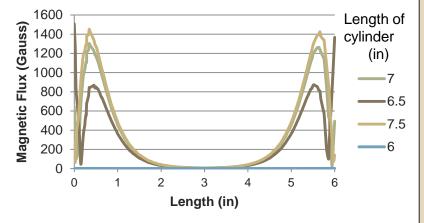


Shielding Box with Core

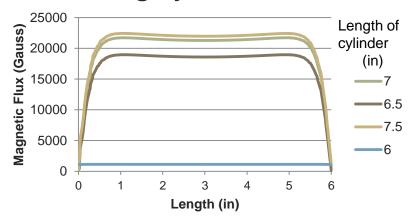








Shielding Cylinder with Core



Deliverables

May 2015

- Compare resonant frequencies of our sample and Mu55
- Prepare MATLAB GUI
- COMSOL simulations using permanent magnets

December 2015

- Magnetic sensor with fewest number of resonant peaks
- Prepare GUI machine interface
- Construct uniform magnetic field generator

What remains

- Measurements of all other client samples to identify amplitudes and frequencies
- Fix the frequency shifting of the spectrum
- Test linewidth and peak detect
- > Determine whether it is possible to interface with inbuilt software. If so do so
- Construction of Solenoid and permanent magnet generator

Thank you

Questions?